ELSEVIER

Artificial Intelligence 103 (1998) 361–362

Artificial Intelligence

Author Index—Volume 103 (1998)

Bibel, W.
Let's plan it deductively! 183–208
Bobrow, D.G. and J.M. Brady
Artificial Intelligence 40 years later 1– 4
Boden, M.A.
Creativity and artificial intelligence 347–356
Brady, J.M., see Bobrow, D.G. 1– 4
Brown, R.D., see Yang, Y. 323–345
Carbonell, J.G., see Yang, Y. 323–345
Castelfranchi, C.
Modelling social action for AI agents 157–182
Chang, S.-F., see McKeown, K.R. 95–116
Dalal, M., see McKeown, K.R. 95–116
Dickmanns, E.D.
Vehicles capable of dynamic vision: a new breed of technical beings? 49– 76
Feiner, S.K., see McKeown, K.R. 95–116
Frederking, R.E., see Yang, Y. 323–345
Huang, T. and S. Russell
Object identification: a Bayesian analysis with application to traffic surveillance 77– 93
Joshi, A.K.
Role of constrained computational systems in natural language processing 117–132
Lin, F.
Applications of the situation calculus to formalizing control and strategic information: the Prolog cut operator 273–294
McKeown, K.R., S.K. Feiner, M. Dalal and S.-F. Chang
Generating multimedia briefings: coordinating language and illustration 95–116
Morgenstern, L.
Inheritance comes of age: applying nonmonotonic techniques to problems in industry 237–271

Elsevier Science B.V.

Motoda, H. and K. Yoshida
Machine learning techniques to make computers easier to use 295–321
Muscettola, N., P.P. Nayak, B. Pell and B.C. Williams
Remote Agent: to boldly go where no AI system has gone before 5– 47
Nayak, P.P., see Muscettola, N. 5– 47
Pell, B., see Muscettola, N. 5– 47
Russell, S., see Huang, T. 77– 93
Steels, L.
The origins of syntax in visually grounded robotic agents 133–156
Van Hentenryck , P.
A gentle introduction to NUMERICA 209–235
Williams, B.C., see Muscettola, N. 5– 47
Yang, Y., J.G. Carbonell, R.D. Brown and R.E. Frederking
Translingual information retrieval: learning from bilingual corpora 323–345
Yoshida, K., see Motoda, H. 295–321